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And the vector directed from P to Q, $\vec{r}_{PQ} = r_Q \hat{a}_Q - r_P \hat{a}_P$ (displacement vector) which is given by $\vec{r}_{PQ} = (x_Q - x_P)\hat{a}_x + (y_Q - y_P)\hat{a}_y + (z_Q - z_P)\hat{a}_z$
The vector \vec{r}_P

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